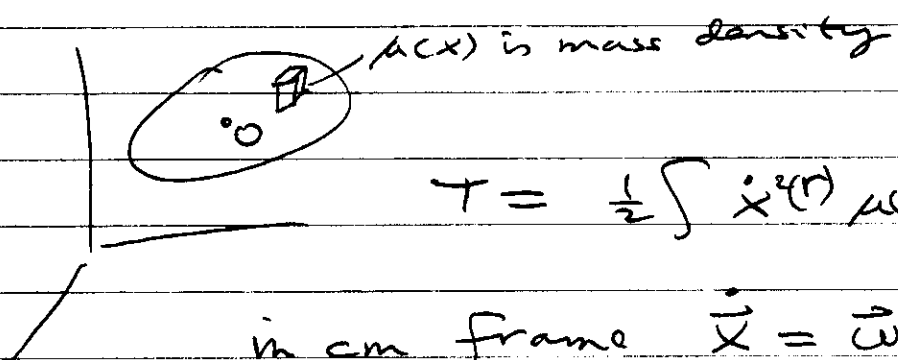


VI.2 Kinetic Energy



$$T = \frac{1}{2} \int \dot{x}^2(r) \mu(r) d^3r$$

in cm frame $\dot{\vec{x}} = \vec{\omega} \times \vec{x}$

$$\Rightarrow \dot{x}^2 = (\vec{\omega} \times \vec{x}) \cdot (\vec{\omega} \times \vec{x}) = \omega^2 x^2 - (\omega \cdot x)^2$$

$$\Rightarrow T = \frac{1}{2} \omega_e \omega_p \underbrace{\int d^3r \mu(r)}_{I_{ep}} (\delta_{ep} x^e - x_e x_p)$$

↑ moment of inertia tensor

Total Kinetic energy

$$T = \frac{1}{2} M V^2 + \frac{1}{2} \sum_{ep} \omega_e I_{ep} \omega_p$$

Note that if we calculate $\frac{1}{2} \sum m (\vec{v} + \vec{\omega} \times \vec{r})^2$ then $\sum m \vec{v} \cdot \vec{\omega} \times \vec{r} = 0$
 " $\sum m \vec{r} \cdot \vec{v} \times \vec{r}$
 " 0 because \vec{r} is w.r.t. cm

$I_{ep} = I_{pe} \Rightarrow I$ can be diagonalized
 $I_{ep} \omega_e \omega_p >$ because $T > 0$