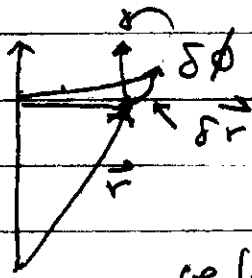


$$\Rightarrow E = \frac{1}{2} m v_0^2 + \underbrace{\frac{1}{2} \sum_k m_k v_k^2}_{\text{kin}} + U$$

IIe) Angular momentum

We consider an infinitesimal rotation



$$\vec{\delta r} = \vec{\delta \phi} \times \vec{r}$$

velocity is also a vector $\Rightarrow \vec{\delta v} = \vec{\delta \phi} \times \vec{v}$

isotropy of space: Lagrangian is invariant under rotations

$$\begin{aligned} \delta L &= \frac{\partial L}{\partial r_k} \delta r_k + \frac{\partial L}{\partial \dot{r}_k} \delta \dot{r}_k \\ &= \underbrace{\frac{\partial L}{\partial r_k}}_{\vec{p}_k} \delta \phi \times \vec{r}_k + \underbrace{\frac{\partial L}{\partial \dot{r}_k}}_{\vec{p}_k} \underbrace{\delta \dot{r}_k}_{\delta \phi \times \dot{r}_k} = 0 \end{aligned}$$

$$\begin{aligned} \Rightarrow \delta L &= \vec{p}_k \cdot \delta \phi \times \vec{r}_k + \vec{p}_k \cdot \delta \phi \times \dot{r}_k \\ &= \delta \phi \cdot (\vec{r}_k \times \vec{p}_k + \dot{r}_k \times \vec{p}_k) \\ &= \delta \phi \cdot \frac{d}{dt} (\vec{r}_k \times \vec{p}_k) = 0 \\ &\quad \uparrow \\ &\quad \text{arbitrary} \Rightarrow \frac{d}{dt} (\vec{r}_k \times \vec{p}_k) = 0 \end{aligned}$$